

What is claimed is:

1. An automatic surveying system comprising:

a telescopic optical system;

an image pickup device for picking up an image

5 of a graduated face of a level rod, to which the telescopic optical system is to be collimated, and converting said image into image data;

10 a memory which stores therein recognition data of at least one of a pattern, numbers, and scale calibrations, provided on the graduated face of the level rod; and

15 an analyzing device for analyzing and recognizing the picked-up image of said at least one of the pattern, numbers, and scale calibrations of the level rod, based on the image data of the level rod picked up by the image pickup device and the recognition data of said pattern, numbers, and scale calibrations, read from the memory, to obtain a measurement.

20 2. An automatic surveying system according to claim 1, comprising:

25 a selection device for selecting recognition data corresponding to a level rod selected from different kinds of level rods, wherein said analyzing device reads said recognition data, corresponding to

the selected level rod, selected by the selection device from the memory.

3. An automatic surveying system, according to claim 1, further comprising an indication device for 5 indicating said measurement obtained by the analyzing device.

4. An automatic surveying system according to claim 1, wherein said analyzing device determines the amount of image data of said level rod in the image width direction based on the image data of the level rod, and performs the analysis based on the amount of the image data thus obtained.

5. An automatic surveying system according to claim 1, wherein said analyzing device determines the amount of image data of said at least one of the pattern, numbers, and the scale calibrations in one of the image width direction and the image height direction, based on the image data of the level rod, and performs the analysis based on the amount of the image data thus obtained.

20 6. An automatic surveying system according to claim 3, wherein said analyzing device recognizes the values of the pattern, numbers, and the scale calibrations which coincide with a predetermined 25 reference line within the field of view of the

telescopic optical system.

7. An automatic surveying system according to claim 6, wherein the telescopic optical system comprises an auto-level collimating telescope, said auto-level collimating telescope including an objective optical system; a focusing optical system; a compensating/erecting optical system, a focusing plate, and an eyepiece optical system, in that order from the object side; and a beam splitter which is provided between the compensating/erecting optical system and the focusing plate to split object image carrying light into one light bundle which is incident upon the eyepiece optical system and another light bundle which is incident upon the image pickup device.

8. An automatic surveying system according to claim 7, wherein said memory device stores therein in advance coordinates on a light receiving surface of an image pickup element on which a horizontal line and a stadia line of the focusing plate are to be formed, so that one of the coordinates of the graduated face of said level rod coincidental with each line and the distance between the lines on the graduated face can be analyzed based on the stored coordinates and the coordinates of the image picked-up by the image pickup device, on the light receiving surface of the image

pickup element.

9. An automatic surveying system according to claim 1, wherein said memory device can store said measurement obtained by the analyzing device.

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